



## PREMIO DI LAUREA “F. SOAVI” 2022

### Scheda sintetica tesi

**Titolo tesi**

Development of an innovative solution for in-process monitoring tool and surface quality in milling operations.

**Relatori**

Prof. Paolo Albertelli

**Autori della tesi**

Ugo Malguzzi

**Presenting author (chi esporrà il lavoro in Assemblea)**

Ugo Malguzzi

**Corso di Laurea Magistrale**

Automation and control engineering

**Università di appartenenza**

Politecnico di Milano

**Abstract del lavoro di tesi (massimo 1000 caratteri)**

Milling is one of the most used industrial processes for machining custom parts, starting from raw workpieces and removing material approaching the desired final product shape. Increasing automation paired with demands from high speed and high performance cutting, leads to the need for **in-process monitoring methods** which gives real-time reliable status indicators, permitting to rise productivity while avoiding waste or faulty conditions. This research describes actual monitoring techniques which make use of sensory machine tools. Starting with the formalization of the milling model, followed by the experimental identification of linked parameters. Kalman Filter was developed and tuned on the identified model to estimate cutting forces and tooltip vibrations based on measurements coming from a sensorized spindle. The limitations of the approach and its robustness were also investigated. Starting from there, innovative methods for **online surface finish evaluation, tool load and wear conditions** are developed. In order to achieve this goal, an algorithm for in-process **engagement estimation** is proposed as well. Simulations and experimental results enhance the performances and possible usefulness of these new methods.

## Immagini illustrative (massimo 3)

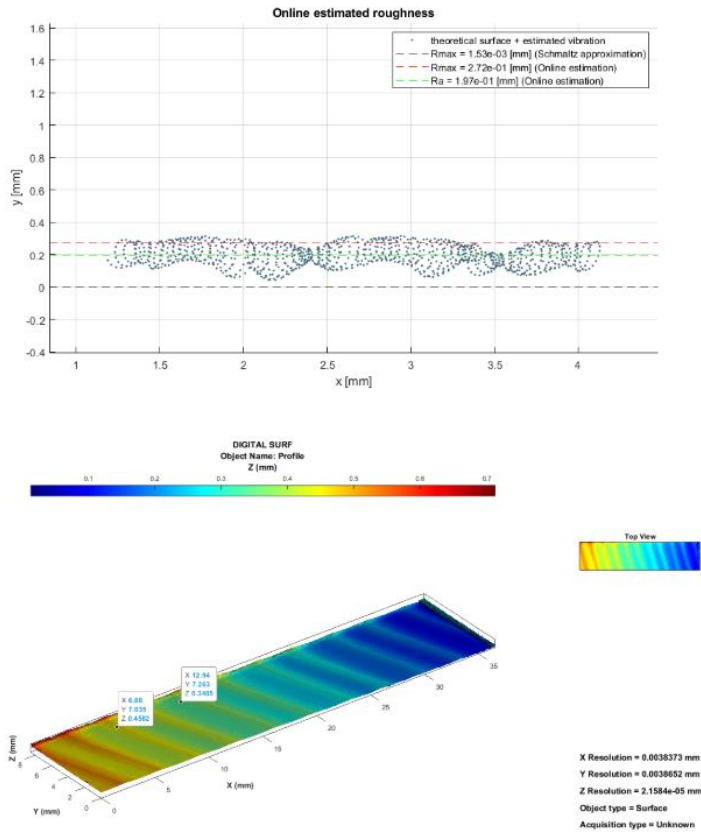


Figure 44: Comparison between estimated and measured roughness, unstable cut

%  
N10 G90 G94 G17 G49 G40 G80  
N15 G21  
N20 T6 M06  
N25 S1000 M03  
N30 G54  
N35 M08  
N40 G00 X-54. Y99.  
N45 G43 Z25. H06  
N50 G00 Z17.  
N55 G18 G02 X-44. Z7. I10. F400.  
N60 G01 X0.  
N65 X100.  
N70 G17 G02 Y38.76 J-30.12  
N75 G01 X0.  
N80 G00 Z25.  
N85 M09  
N90 G49  
N95 M30  
%

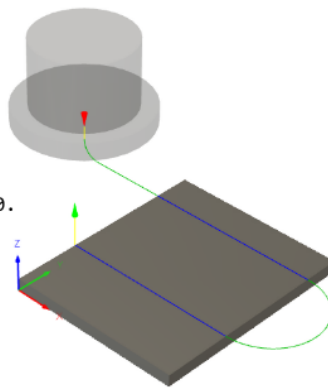


Figure 45: Tested toolpath and corresponding G-code

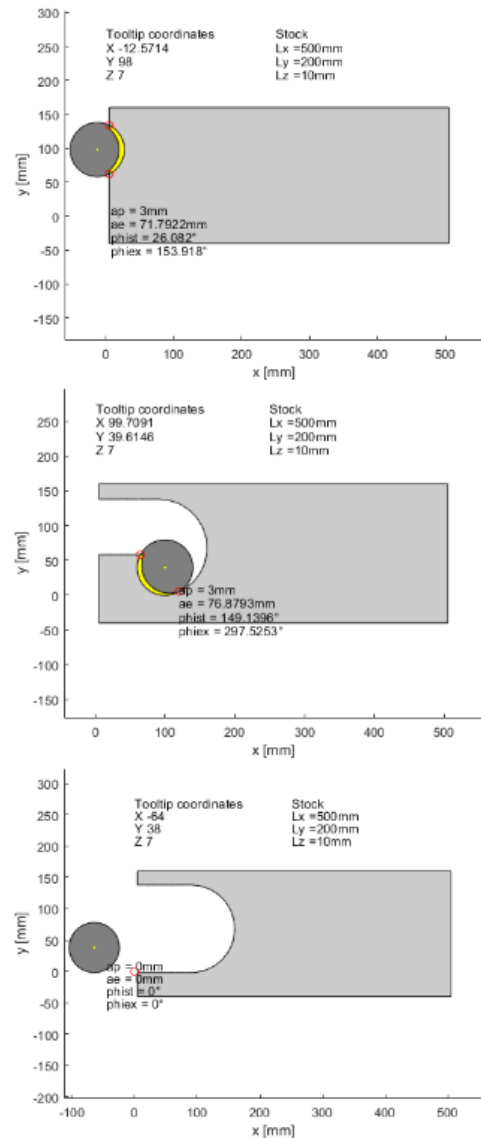


Figure 46: Simulation of engagement estimation algorithm